

Investor Presentation

Spring 2017

Fizikl is developing an automated inventory counting program, fusing inputs from cameras and sensors on drones, robots and stationary devices with artificial intelligence to continuously cycle count items in inventory.

Proof-of-Concept by June, 2017 • MVP by YE, 2017





Fizikl is a play on the short-hand reference to doing physical inventory.

US industry and trade **spends** over



in labor taking physical inventory

- Involves stopping primary work and spending weekends, holidays counting
- Boring, laborious, monotonous, error prone, manual work
- Errors disappoint customers when goods are thought to be in stock, or
- Cause waste when undercount results in extra inventory purchases
- Zero top line benefit to business
- Required by Auditors, SEC to reconcile the inventory asset
- Traditional Bricks & Mortar losing share to Amazon.com, need to "digitize" to compete

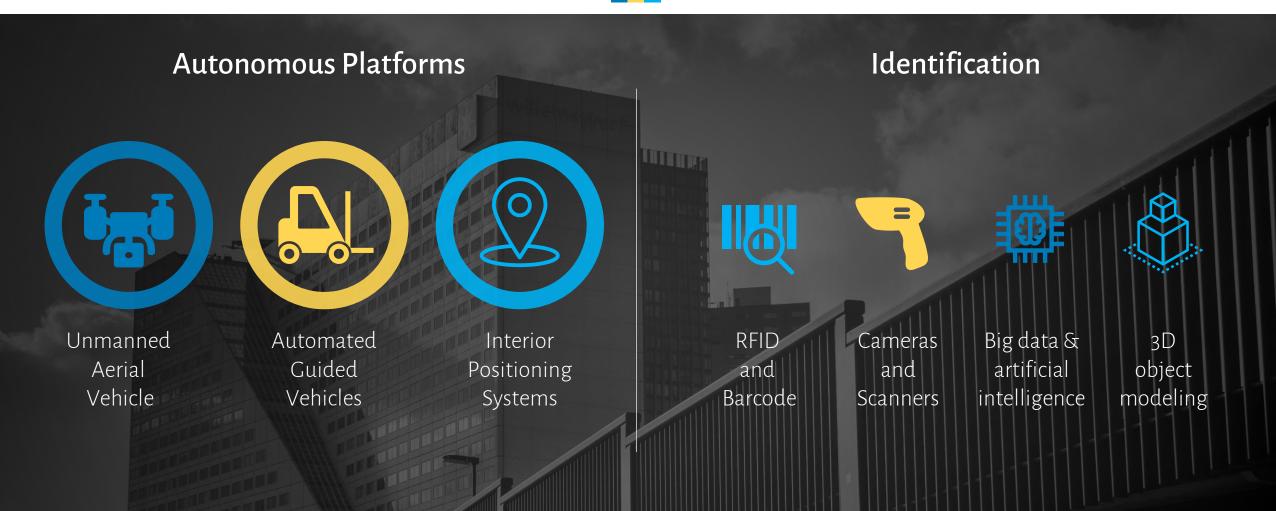
Addressable Market





Emerging Technology

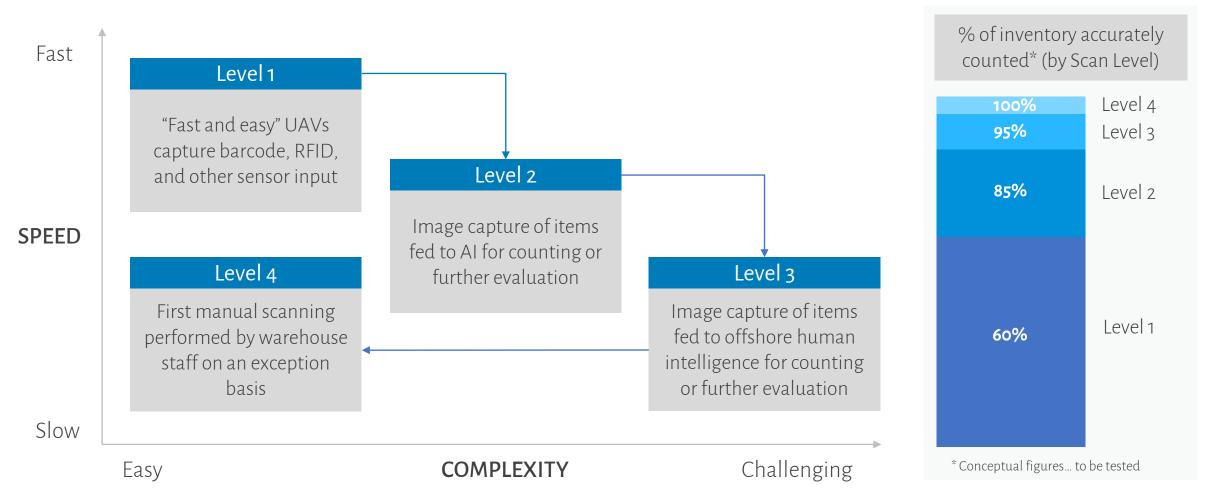
Opportunity arises from convergence of developing technology





Conceptual Product Overview

After hours, Fizikl's system counts warehouse items, then provides count to customer's management for reconciliation the following day.





Convergence Technology

Fizikl's "secret sauce" is how it couples existing technologies to automate the inventory counting process in a proprietary way.



Machine Vision

Using RGB cameras, barcodes on item labels are captured from video streamed from UAVs to base station where they are compared to reference database

Neural Net technology (AI) used to recognize items in video stream and infer box topology and box count

Using depth cameras, we create 3D object models for manual counting by offshore human intelligence where needed



Autonomous Vehicles

UAVs– Flying platform for cameras

Robots (AGVs) – in some warehouses AGVs move cameras mounted on booms to image all sides of pallets to stream video

Indoor navigation – system capable of navigating using ultrasonic beacons as well as Visual Light Communication and other indoor navigation systems



AI and Software

Standard input and output with csv files: ERP and WMS agnostic

Pallet, case and SKU description weight and dimension database

Sensor fusion – from camera input and, as needed, weight from bin sensors

Al compares target image to database of standard images to recognize items, brain develops confidence factor as it learns over time



Project Deliverables

Project team is developing Proof-of-Concept by July , Minimum Viable Product (MVP) by YE 2017



Delivered by end the end of year

- Demo of drone automatically navigating a warehouse, ID items using barcode AutoID
- 2. Demo of 3D image of item being captured, ID with confidence percentage

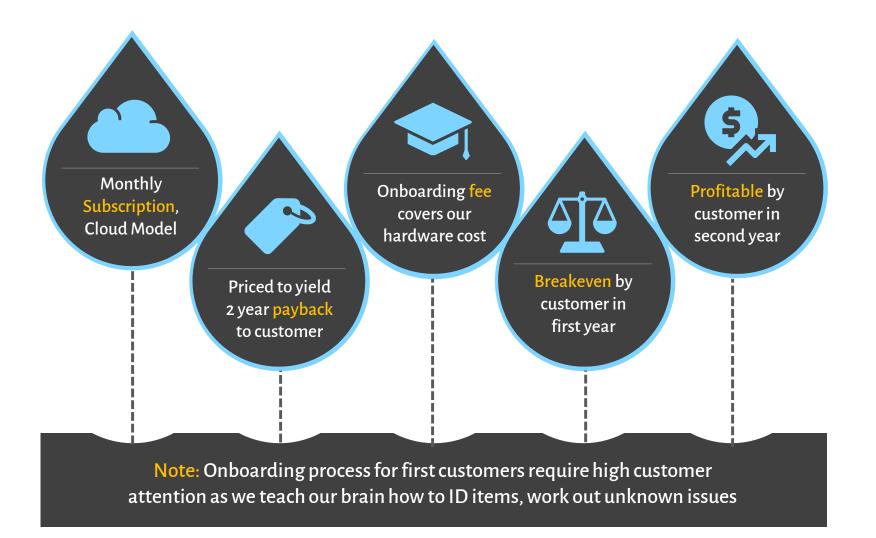
Delivered by end of July 2017

3. Software architecture complete, backend framework functional, partial UI developed

- 4. Demo of UAVs and AGVs, each using the technologies (scanning, modeling, learning) to count items on warehouse shelves.
- 5. Product cost review capital and operating expenses
- 6. First version UI and cloud based software complete
- Business plan components, including market scope, go to market strategy, staffing, financial forecast, and funding strategy



Business Model



Starter Kit ~\$8,700

Intel Aero UAV Base Station Laptop, preconfigured connectivity Charging landing pad Indoor navigation beacons







Customer #1

Sonepar, the World's largest electrical products distributor (+\$20B revenue), has agreed to be our first customer

- Agreement is contingent upon successful development of equipment and technology
- Sonepar facility to be utilized for a trial, including test inventory
- Physical inventory data to be provided to Fizikl for use in test database at University of Washington
- Sonepar key management participation

Customer Advisory Group (accounting, operations) Market Research (distribution focus, technology) Project coordination (facilities, inventory, access)



October 31, 2016

Dave Gabriel North America Region President Sonepar N.A., Inc. 4400 Leeds Avenue, Suite 500 Charleston SC 29405

Re: Proposal

Dear Mr. Gabriel

In discussions with Mark Pedro I understand you are interested in the idea that FizikI can develop methods of taking physical inventory automatically, using software, drones and robots. The goal is to offer customers such as Sonepar the means of increasing the accuracy of inventory count while saving the labor cost and disruption of taking physical inventory.

We have secured initial seed investment in this concept, as well as an indication of support in the form of cash and in-kind contribution from a strategic investor. We are seeking your commitment to be a trial customer, once we have developed our product. The purpose of this proposal is to set out the terms of such a trial.

Fizikl is currently developing the specification of a minimum viable product ("MVP") and negotiating the terms under which we will build a laboratory and work with the engineering departments at the University of Washington. Once functionality has been proven at UW, in roughly 12 to 18 months' time, we want to deploy the system in a functioning warehouse to test performance. We ask that Sonepar allow Fizikl to work in a warehouse of its choosing for that purpose. Our work will be performed during non-operating hours and we intend to not disrupt normal business operations in any way.

Fizikl MVP

We envision our Fizikl product to be deployed and function in the following manner; note steps 1 to 5 are preparatory, taking place in the weeks prior to deployment:

- 1. Prepare warehouse environment including installing Visual Light Communication (VLC) and
- mapping the space.

 Install Unmanned Aerial Vehicle (UAV) & Automated Guided Vehicle (AGV) bases with charging capability
- 3. Enable VLC downlink for indoor positioning
- Install and enable wireless radio link for two-way communication
- Obtain SKU data from ERP for reference
- Includes expected location addresses and quantity
- Received as CSV file

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support in helping us develop our product, we offer to sell you 3 be deployed at the North American location of your choice. We will pport as we would any customer purchasing at full price.

a contraction of a contract parameter parameter pro-

and agreed to this ______ day of _______, 2016, by



G. GABRIEC



lorth America

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Go to Market Strategy

Securing a beachhead in electrical distribution vertical (\$60M addressable market), then rapidly expand to include electrical parts manufacturers.

Electrical Parts Distributors							
	Distributor	Annual Revenue	Avg. Inv. Value	Physical Cost			
1	Sonepar (North America)	9,600	700	6.0			
2	WESCO International	7,500	832	7.1			
3	Graybar	6,100	445	3.8			
4	Rexel	5,600	621	5.3			
5	CED	5,500	610	5.2			
6	Anixter	4,800	1182	10.1			
7	Border States	1,500	166	1.4			
8	Crescent Electric	1,100	122	1.0			
9	City Electric Supply	1,000	111	1.0			
10	W.W. Grainger	997	1409	12.1			
11	Mayer Electric Supply	811	90	0.8			
12	EIS	752	83	0.7			
13	Elliot Electric Supply	742	82	0.7			
14	McNaughton-McKay Electric	500	55	0.5			
15	The Reynolds Company	500	55	0.5			
16	States Electric Supply	500	55	0.5			
17	North Coast Electric	475	53	0.5			
18	Turtle & Hughes	450	50	0.4			
19	Kendall Electric	450	50	0.4			
20	Summit Electric Supply	426	47	0.4			
	Total Physical Inventory Cost			58.4			



Source: Modern Distribution Management "2016 Top Distribution Companies", Public company data, Google Finance, and Fizikl estimates.

Go to Market Strategy

Physical inventory costs more than \$80 million in the top 20 industrial distributors. Industry "verticals" will guide selling prioritization.

				Primary Verticals		Opportunistic Verticals			Out of Scope								
		Average	Annual	Industrial						Indust.	Power			Hose &	Gases and		
	Distributor	Inventory	Physical Cost	Products	Electrical	HVACR	Satefy	Fasteners	Fluid Power	PVF	Trans	Jan-San	Bldg. Mat'l	Access	Welding	Electronics	Plastics
1	W.W. Grainger	1,409	12	•	•	•	•	•	•		•	•					
2	HD Supply	852	7	O									Ð				
3	Airgas	469	4	0			0								0		
4	Motion Industries	708	6	•					•		•						
5	MRC Clobal Corp.	693	6	O						Ð							
6	The Fastenal Company	978	8	•			•	•	•			•					
7	NOW, Inc.	462	4	O						Ð							
8	MSC Industrial Direct	356	3	•				•									
9	McMaster-Carr	431	4	•				•									
10	Winsupply	416	4	•		•											
11	Applied Industrial Tech	344	3	•					•		•						
12	Sonepar (North America)	700	6	•	•		•										
13	Edgen Murray	388	3	O						Ð		O					
14	Interline Brands	262	2	•		•											
15	Wurth-Americas	262	2	•				•									
16	Wolseley Industrial	216	2	•				•		•							
17	DXP Enteprises	102	1	•			•				•						
18	Kaman Distribution	392	3	O					O		O						
19	F.W. Webb	148	1	•		•											
20	ERIKS North America	122	1	0													

Use of Funds: Cash Flow Planning

Investment	Less closed Sept. '16 \$15	<mark>00 K</mark> 50 K 50 K	2 nd SEED FINANCING \$500 K (Q3 2017)	SERIES A ~\$2.0 MM Q4 2017 – Q1 2018
	Months 1-6		Months 7-12	
Milestones {		Proof of Con June 2		emo, Year-End 2017
(UW Sponsored Research	\$110	Capital Expenditures	\$110
	Capital Expenditures	40	Fizikl R&D Salaries	40
	Administrative & Travel	75	Administrative and Travel	75
Uses of Funds \prec	Project Management	45	Project Management	45
	Subtotal	270	Subtotal	270
	Contingency	25	Contingency	25
	Total	295	Total	295



Timing is everything

"

Your project is exciting, right on the edge of what is needed commercially and what the computer world is capable of addressing.

"

It is amazing how fast you have been able to recruit professors to help you, I think it is because you are giving them a challenge that is just within the reach of their most exciting breakthrough technology.

"

When the time is right I'll introduce you to Amazon's VP Logistics. If you can pull this off they will buy you in a heartbeat.

Lucas Dixon, Google Jigsaw (When referencing Checking CTO candidate) **Mohan, Vaghul** (UW CoMotion EIR and OneRadio, Inc. CEO) Ian MacDuff, VP Business Development (Product Creation Studio, Seattle, WA)



The next chapter

Fizikl has committed to the UW project to POC Angel **investment** \$150K March'17 + \$550K July'17

\$

UW project to MVP, **Hire** software engineers, build UI and data management Sonepar to support commercially during commercial scale-up Venture Capital **funded** Series A ~\$2.0mm

\$



Team

Fizikl

TOM MALONE



CEO & Founder Entrepreneur-In-Residence at UW

• 4 prior startups

- MBA, Pepperdine University
- www.linkedin.com/in/thomasgmalone



MARK PEDRO

CFO & Founder Former CFO Sonepar N.A.

- Product Visionary
- MBA UCLA
- www.linkedin.com/in/markpedro

KEVIN DIBBLE

Consulting with expectation to join as CTO

- Seasoned software executive, Agile guru
- 5 prior start-ups, track record of building technology companies.
- www.linkedin.com/in/kevin-dibble-0a35032

UW

KRISTI MORGANSEN

- PhD, Professor in the Williams E. Boeing Department of Aeronautics & Astronautics,
- UW (CalTech, Harvard, Boston U.
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UNSIK LEE

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- UW
- http://rain.aa.washington.edu/ Group_Members/Unsik_Lee

CARLO PASCUCCI

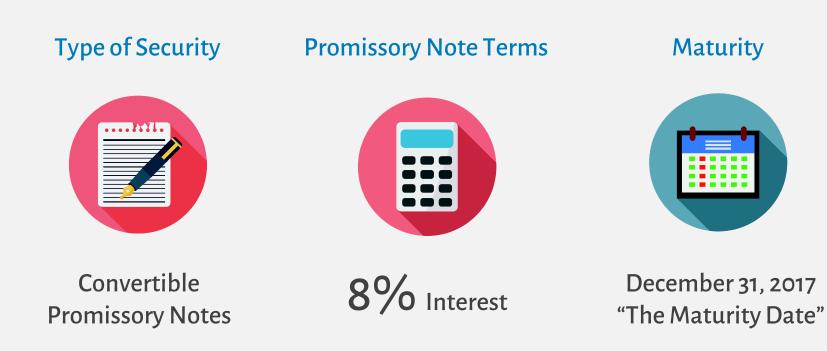
- PhD PostDoc Fellow
- A&A Engineering
- Aeronautical Engineering, Electronic Engineering, Control Systems Engineering
- https://www.researchgate.net /profile/Carlo_Pascucci



APPENDIX ITEMS



Seed Financing Terms



Conversion Rights

The principal and interest will convert into the Company's next equity financing (the "Next Equity Financing") on the same terms as the Next Equity Financing; provided the Notes shall convert at a price per share equal to 80% of the per share price paid by outside investors in the Next Equity Financing.



Product Development Underway at UW

Objective: Build a fully autonomous and scalable system composed of quadrotors and ground robots with a base station to plan and to execute safe motion through a warehouse, maintain an inventory of all items in the space, identify unknown items, and update the inventory at a known rate.



- Select computing platform
- Develop communication links to "base station" computer and vehicles
- Develop software to link system to real-time control/ID system

VEHICLE HARDWARE

• Select vehicle platforms and sensors

2

- Integrate sensors and scanners on all vehicles
- Integrate "auto-pilot" with base station

VEHICLE MOTION CONTROL

- Develop navigational algorithms and implement
- Develop two-stage waypoint algorithm move vehicle to points and scan
- Integrate obstacle avoidance

3

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4 VEHICLE TRAJECTORY PLANNING

- Construct trajectory plans for known, partially known, and unknown inventory layouts
- Incorporate autonomous recharging
- Develop multi-UAV system

5 3D MODELING & OBJECT ID

- Generate 3D models of sample warehouse items
- Develop algorithms to match 3D object models to items in warehouse

INVENTORY ITEM ID

- Build process for sending ID query to update vehicle trajectory
- Determine serial vs. parallel structuring of operations (motion, trajectory and ID)



Development "Towers"

Objective: Build a fully autonomous and scalable system composed of quadrotors and ground robots with a base station to plan and to execute safe motion through a warehouse, maintain an inventory of all items in the space, identify unknown items, and update the inventory at a known rate.

	Autonomous Platform	Identification	Data & Communication			
Critical Technologies and Capabilities	 Navigation – Interior Positioning Systems Unmanned Aerial Vehicles Automated Guided Vehicles Scanners (RFID, Barcode, 3D) Base Station Computing Power Management 	 Identification of Unknown Items, Sensor Fusion and 3D Object Modeling Scanners (RFID, Barcode, 3D) Predictive Analytics Algorithms Warehouse Item Identification Warehouse Item Tracking 	 Identification of Unknown Items, Sensor Fusion and 3D Object Modeling Scanners (RFID, Barcode, 3D) Predictive Analytics Algorithms Warehouse Item Identification Warehouse Item Tracking 			
Responsibilities	UW – Morgansen and Burden	UW – Morgansen and Fox	Fizikl and VLC Partner			
Key Question for Project Viability	Is the VLC technology sufficient to allow indoor navigation, manipulation and operation of drones?	Will 3D object modeling provide adequate quality digital images to enable unknown object identification?	Will data flow fast enough to make ID decisions timely?			